

# LCLS Control System Status

## EPICS Collaboration Meeting

### October 6-7, 2005

#### ■ Outline

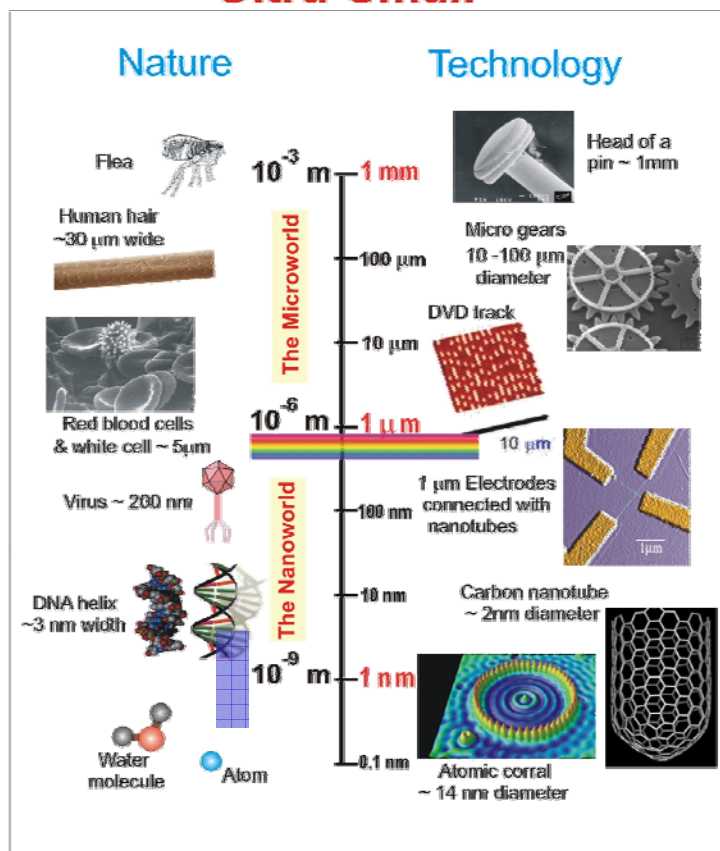
- Project Overview
- Control System Goals
- Resources
- Design Slides for Global Systems
- Tools/ Standards to adopt from the community for LCLS
- Status
- Conclusions

# The World's First Hard X-ray Laser

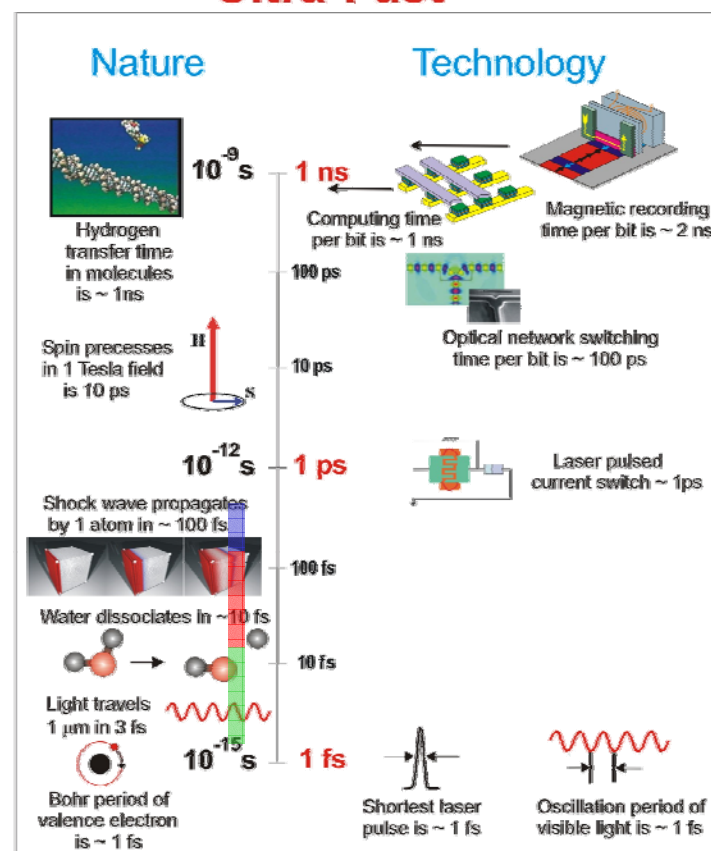
## Laser

X-FELs open the Ultra-Small and Ultra-Fast Worlds

### Ultra-Small



### Ultra-Fast



# Capabilities

Spectral coverage: 0.15-1.5 nm

To 0.5 Å in 3<sup>rd</sup> harmonic

Peak Brightness:  $10^{33}$

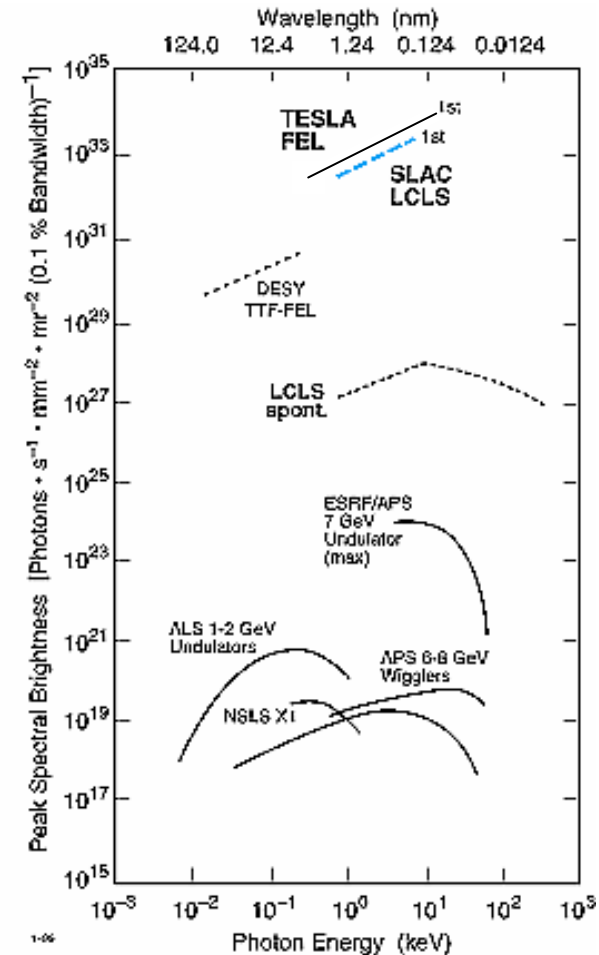
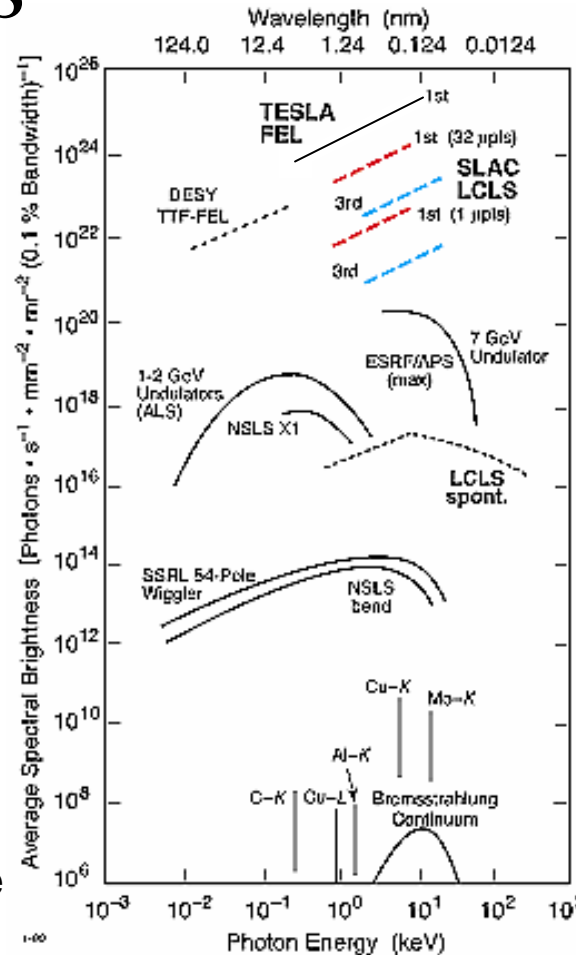
Photons/pulse:  $10^{12}$

Average Brightness:  $3 \times 10^{22}$

Pulse duration: <230 fs

Pulse repetition rate: 120 Hz

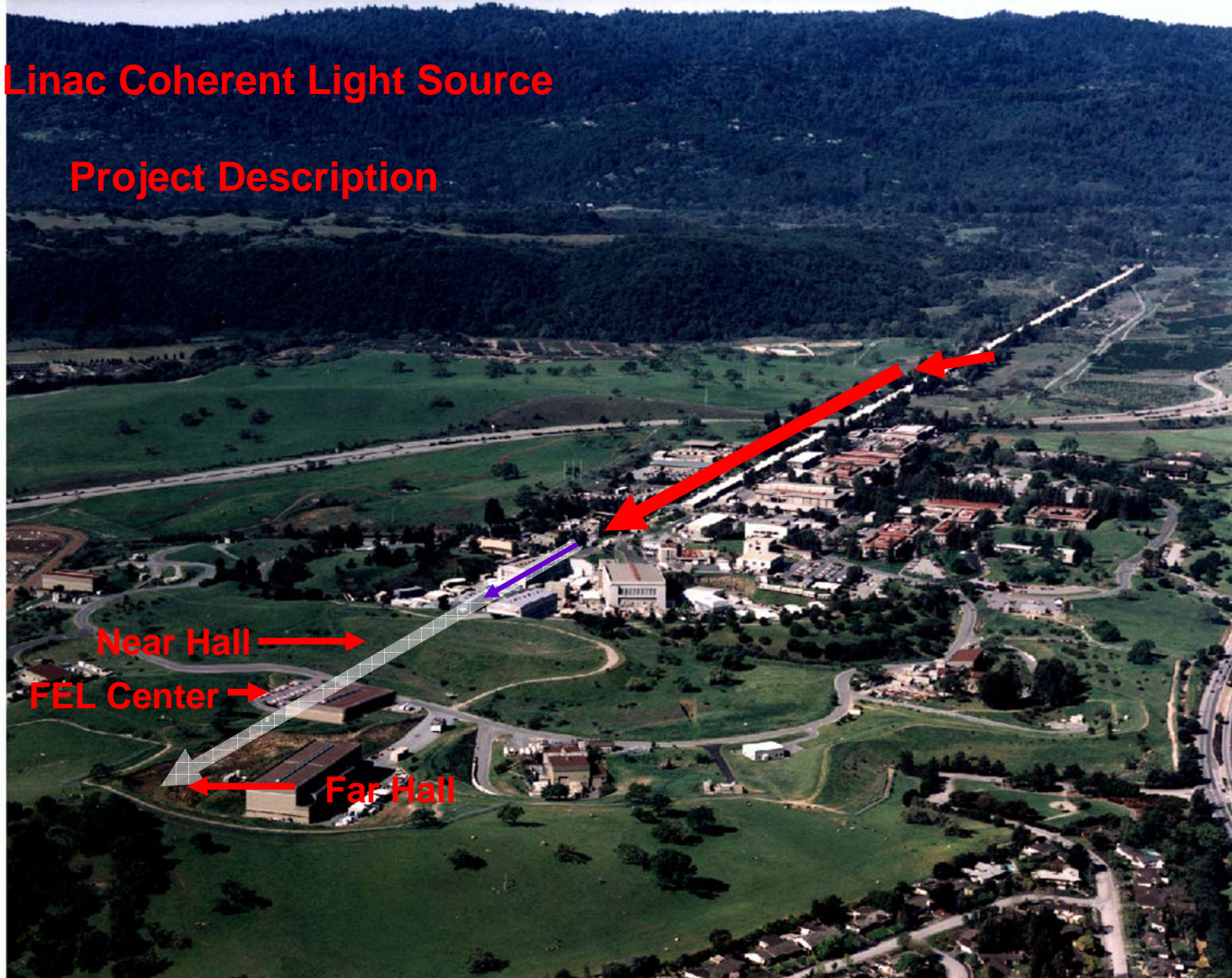
Upgrade – more bunches/pulse





# Linac Coherent Light Source

## Project Description



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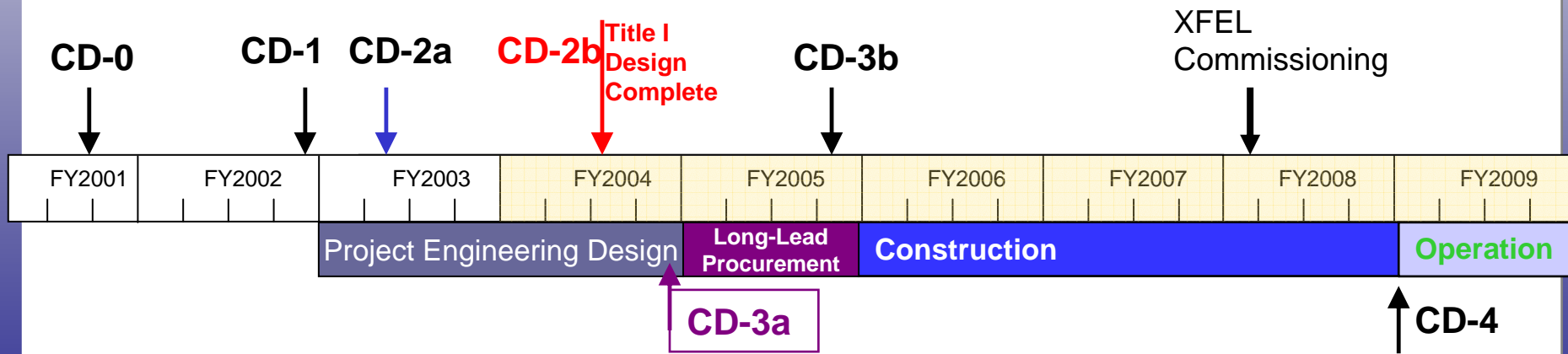
[dalesio@slac.stanford.edu](mailto:dalesio@slac.stanford.edu)



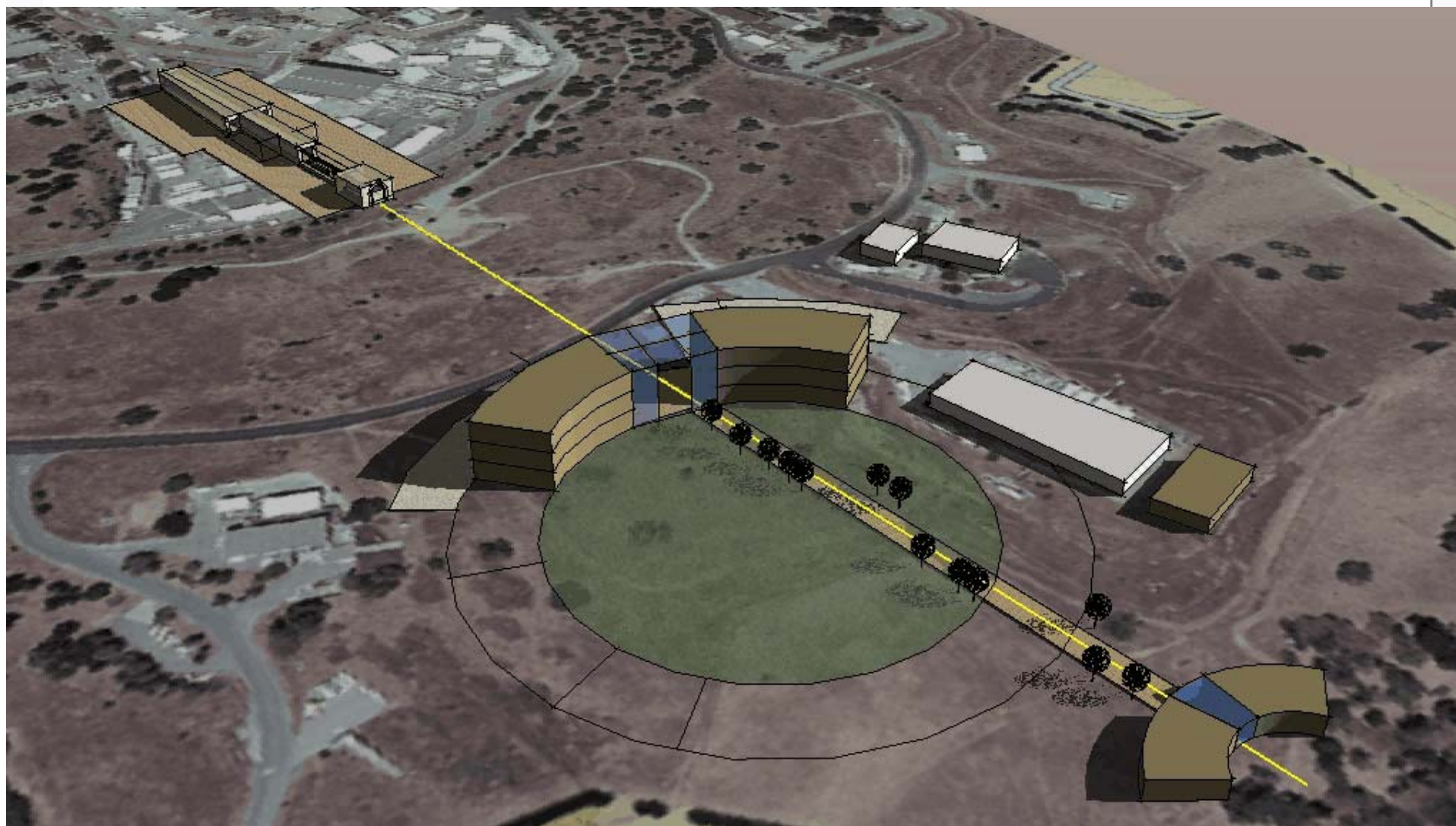
# LCLS - Estimated Cost, Schedule

## ■ \$379M Total Project Cost

- **FY2005** Long-lead purchases for injector, undulator
- **FY2006** Construction begins
- **FY2007** FEL Commissioning begins
- **September 2008** Construction complete – operations begins







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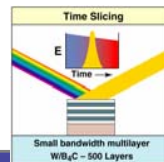
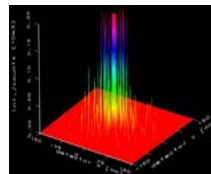
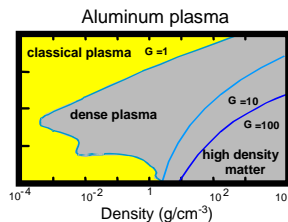
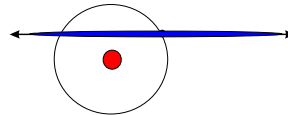
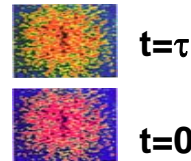
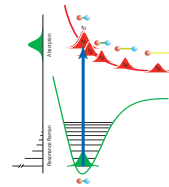


•SLAC-PUB-611



Program developed by international team of scientists working with accelerator and laser physics communities

*“the beginning.... not the end”*



**Femtochemistry**

**Nanoscale Dynamics in Condensed matter**

**Atomic Physics**

**Plasma and Warm Dense Matter**

**Structural Studies on Single Particles and Biomolecules**

**FEL Science/Technology**

## LCLS Control System Goals

- Provide a fully integrated control system to support the construction, test, installation, integration, operation and automation of the LCLS Accelerator
- Standardize all devices and components across all subsystems.
- Identify all data either by pulse id, beam pulse related time stamp, or 500 msec rough time stamp.
- Full integration with the SLC – timing, use of LCLS data in SLC high level applications, and use of SLC data in LCLS



# Personnel – Resources FY 2005

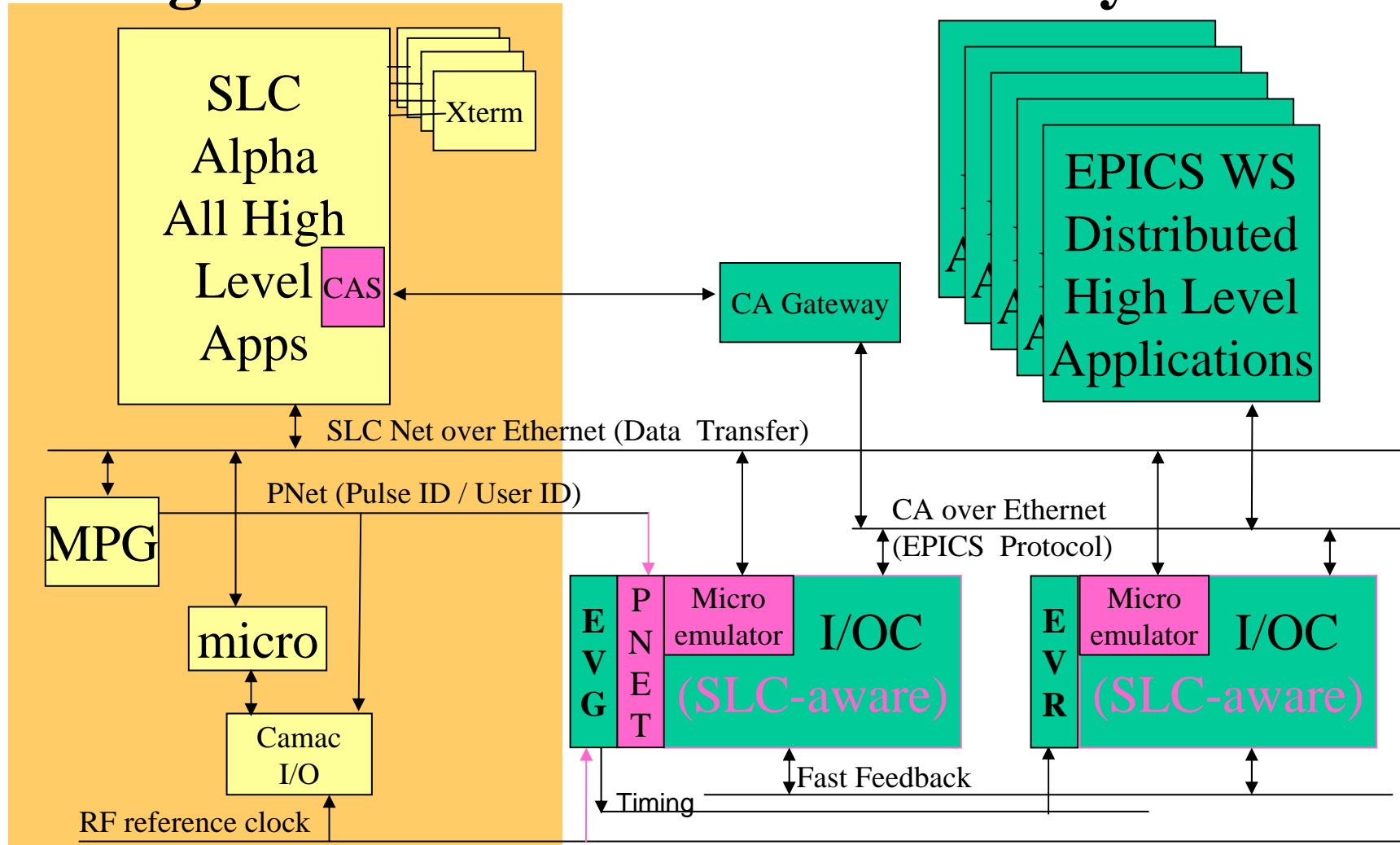
	Q1	Q2	Q3	Q4	06 Q1
Ctl. Elec. Engineer	0.75	4.35	7.35	7.35	7.35
Ctl. Sr. Elec. Tech.		1.11	3.35	3.35	3.35
Ctl. Elec Tech.		0.56	0.56	0.73	1.96
Pwr. Elec. Engineer		1.32	1.32	1.32	1.32
Pwr. Sr. Elec. Tech.		0.35	0.61	0.62	.62
Control Prog.	3.50	7.14	10.63	10.63	10.63

Dayle Koturri  
Mario Ortega  
Sheng Peng  
Kristi Luchini  
Stephen Norum  
Sergei Chevstov  
Doug Murray  
Artura Alacron  
Stephen Schuh  
Michael Cecere

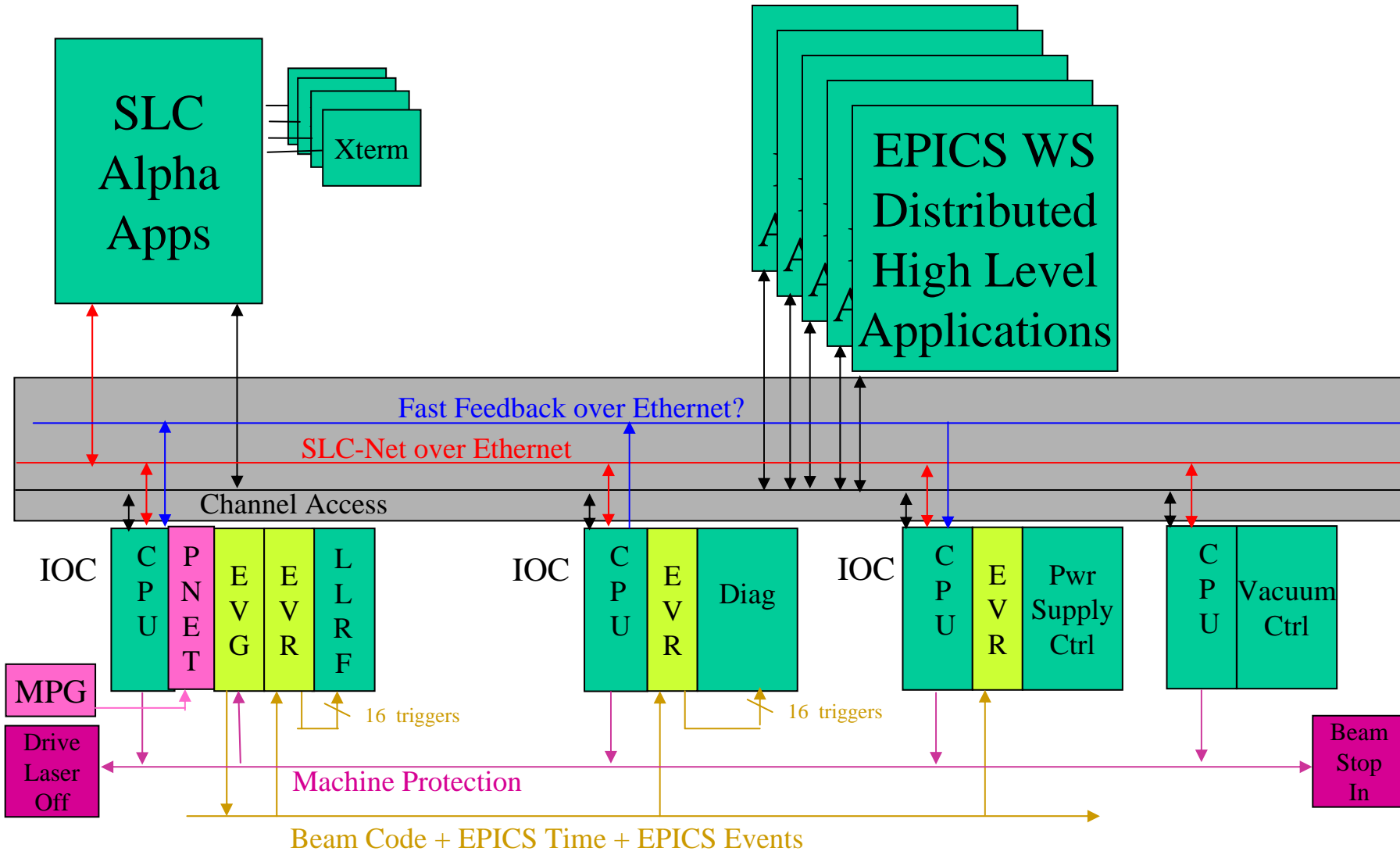
Stephanie Allison (SSRL)  
Tilli Strauman (SSRL)  
Debbie ROgind (ESD)  
Diane Failrey (ESD)  
Paul Bellermo (ESD)  
Tom Porter (ESD)  
Bob Fuller (EsD)  
Antonio Delira (ESD)  
Dave Manair (ESD)  
Support from others as needed

↑  
**Fully staffed**

# Integration with the SLC Control System



# Global Communication Buses





# Environment

■ EPICS Release	3.14.n
■ R/T OS	RTEMS
■ Workstation OS	LINUX
■ EPICS ADE (CVS)	Simple??
■ Compilers	GNU
■ Bug Report / Tracking	Artemis
■ Naming Standard	PEP II
■ Name Service	Name Server JLAB
■ Documentation	Web Area
■ Test stations	Lab / FFTB? / SLC

## Client Tools

- |                       |                    |
|-----------------------|--------------------|
| ■ Display Manager     | EDM                |
| ■ Archiver            | Channel Archiver   |
| ■ Alarm Handler       | ALH                |
| ■ Message Logger      | CMLog              |
| ■ Electronic Log Book | DESY, Babar, JLAB? |
| ■ Stripchart          | StripTool          |
| ■ Web based viewing   | EPICS Office??     |
| ■ Image Analysis      | Matlab format?     |
| ■ Save / Restore      | ?                  |
| ■ RDB                 | PEP derivative     |
| ■ Gateway             | 3.14.6 Gateway     |

# High Level Applications

- Matlab Available for Physicists
- Python Available for Physicists
- High Level Apps
  - SLC Available in existing system
  - XAL New direction
  - Matlab based Growing group of users
- Top priorities to move into EPICS
  - Which ones make the SLC-aware IOC easier
  - Which are the most useful
  - Which are the easiest to pick off



## Hardware Direction – Buy/Steal/Make

- In-House VME version of the PNET
- Commercial BPM - Echotek digitizer / analog f/e
- Community Timing System (Diamond)
- Community Power Supply Controller (uIOC)
- Commercial LLRF – Digitizers / analog f/e (uIOC)
- Community Machine Protection System (uIOC)  
8msec Shut off
- Commercial Video – evaluate several options (30 Hz)
- Commercial Conventional Facilities through ALC
- Community Motion Control using Newport Motors
- Commercial Fast feedback: Shared Mem / 2<sup>nd</sup> Ethernet?

## Status

- Complete SLC-aware IOC (100% Complete)
- Complete PNET Prototype (100% Complete)
- Complete Timing Prototype (75% Complete)
- Complete BPM Prototype (20% Complete)
- Complete Power Supply Prototype (10% Complete)
- Complete Video Prototype (25% Complete)
- Design Document for Machine Protection System – determine if there is something that we can evaluate (45% Complete)
- Integrate Facility Controls, XRay Transport (75% Complete)
- High Level Applications now have a team starting

## Next 6 Months

- Complete BPM Prototype
- Complete Timing Prototype
- Complete Power Supply Prototype
- Complete Video Prototype
- Design Document for Machine Protection System
- High Level Applications
  - XAL Orbit Display
  - Emittance Measurement



# Installation Schedule

■ Laser	5/1/2006 –05/31/2006
■ Injector, Injector Spectrometer	9/1/2006 - 11/02/2006
■ Linac L1 and Bunch Compressor 1	9/1/2006 - 11/02/2006
■ Linac L2, Bunch Comp. 2, and L3	8/1/2007 - 10/31/2007
■ Linac to Undulator	11/1/2007- 1/31/2008
■ E-Dump	11/1/2007- 1/31/2008

## Conclusions

- We have a great team in place.
- Integration with the existing SLC system is a critical step to allow SLAC operators to use the existing tools while we are adopting and modifying replacements.
- Standard EPICS tools for core development and engineering interfaces are in use.
- Most of our hardware is based on developments from the community or those commercially available.
- Embedded controllers are being evaluated for Power Supply, LLRF, MPS, Vacuum and Video Control.
- Effort to expand high level applications is started.